

③9 (a)  $\boxed{\dot{v} = -\alpha v + \beta \frac{1}{t} \ln\left(\frac{v}{v_0}\right), v(0) = v_0}$

(b) Da, wird  $v < v_0$  und, d.h. ln negativ  $\textcircled{O}$

(c)  $[\beta] = [\dot{v}t] = [v] \Rightarrow \beta < v_0 \text{ } \textcircled{O}$

(d)  $\boxed{\dot{v}'(0) = -\alpha v'(0), v'(0)(0) = v_0} \Rightarrow v'(0)(t) = v_0 e^{-\alpha t} \text{ } \textcircled{O}$

$$\dot{v}'' = -\alpha v'' + \beta \frac{1}{t^2} \ln\left(\frac{v'(0)}{v_0}\right)$$

$$\boxed{\dot{v}'' = -\alpha v'' - \alpha \beta, v''(0) = 0} \Rightarrow v''(t) = -\beta + \beta e^{-\alpha t} \text{ } \textcircled{O}$$

④0 (a)  $\partial_x \arctan(x) = \frac{1}{1+x^2} = \sum_{n=0}^{\infty} (-x^2)^n = 1 - x^2 + x^4 - \dots \text{ } \textcircled{O}$

$\Rightarrow \arctan(x) = \text{const.} + x - \frac{1}{3}x^3 + \frac{1}{5}x^5 - \dots$ , const =  $\arctan(0) = 0 \text{ } \textcircled{O}$

(b)  $\tan(x) = \frac{x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots}{1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots} = \left(x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots\right) \left(1 + \frac{x^2}{2!} - \frac{x^4}{4!} + \left(\frac{x^2}{2!}\right)^2 + \dots\right)$   
 $= x + \frac{1}{3}x^3 + \frac{2}{15}x^5 + \dots \text{ } \textcircled{O}$

(c)  $mc^2(1-\varepsilon^2)^{-\frac{1}{2}} = mc^2 \left(1 - \frac{1}{2}(-\varepsilon^2) + \frac{1}{2}(-\frac{1}{2})(-\frac{3}{2})(-\varepsilon^2)^2 + \dots\right) = mc^2 + \frac{1}{2}mv^2 + \frac{3}{8} \frac{mv^4}{c^2} + \dots \text{ } \textcircled{O}$

(d)  $mc^2 \sqrt{1 + \frac{p^2}{m^2 c^2}} = mc^2 (1 + \varepsilon^2)^{\frac{1}{2}} = mc^2 \left(1 + \frac{1}{2}\varepsilon^2 + \frac{1}{2}\frac{1}{2}(-\frac{1}{2})\varepsilon^4 + \dots\right) = mc^2 + \frac{1}{2} \frac{p^2}{m} - \frac{1}{8} \frac{p^4}{m^3 c^2} \text{ } \textcircled{O}$

④1 (a)  $M\ddot{v}_1 = -M_\alpha(v_1 - v_2)$      $\boxed{M\ddot{v}_2 = -M_\alpha(v_2 - v_1)}$      $\ddot{v} = -\alpha H \vec{v}, H = \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \text{ } \textcircled{O}$

(b) EV:  $f_{12} = \frac{1}{T_2} \begin{pmatrix} 1 \\ \pm 1 \end{pmatrix} \text{ } \textcircled{O}$  (und EW:  $\lambda_{12} = \left\{ \frac{0}{2}, \frac{0}{2} \right\}$ )

Ansatz  $\vec{v} = A(t)\vec{f}_1 + B(t)\vec{f}_2$  in ER:

$$\dot{A}\vec{f}_1 + \dot{B}\vec{f}_2 = -\alpha \vec{f}_2, A(0)\vec{f}_1 + B(0)\vec{f}_2 = \frac{v_0}{T_2} (\vec{f}_1 + \vec{f}_2)$$

$$\Rightarrow \boxed{\dot{A} = 0, A(0) = \frac{v_0}{T_2}; \dot{B} = -2\alpha B, B(0) = \frac{v_0}{T_2}} \text{ } \textcircled{O}$$

$$\text{Lsg} \Rightarrow A(t) = \frac{v_0}{T_2}; B(t) = \frac{v_0}{T_2} e^{-2\alpha t} \text{ } \textcircled{O}$$

$$\text{also } \vec{v}(t) = \frac{v_0}{T_2} \frac{1}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \frac{v_0}{T_2} \frac{1}{2} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \frac{v_0}{2} \begin{pmatrix} 1 + e^{-2\alpha t} \\ 1 - e^{-2\alpha t} \end{pmatrix} = v_0 e^{-\alpha t} \begin{pmatrix} \cos(\alpha t) \\ \sin(\alpha t) \end{pmatrix} \text{ } \textcircled{O}$$

und  $\vec{v}(t \rightarrow \infty) = \frac{v_0}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \text{ } \textcircled{O}$ , sehr langsam!

(c)  $\vec{v}(t) = e^{-\alpha H t} v_0 \begin{pmatrix} 1 \\ 0 \end{pmatrix} \text{ } \textcircled{O}$

$$= e^{-\alpha t} \underbrace{\left[ e^{+\alpha R t} \right]}_{R = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}}, \text{ mit } R = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, R^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathbb{1} \text{ } \textcircled{O}$$

$$= \mathbb{1} + \alpha t R + \frac{1}{2!} (\alpha t)^2 \underbrace{R \cdot R}_{= \mathbb{1}} + \frac{1}{3!} (\alpha t)^3 \underbrace{R \cdot R \cdot R}_{= \mathbb{1} \cdot \mathbb{1} = \mathbb{1}} + \frac{1}{4!} (\alpha t)^4 \underbrace{R \cdot R \cdot R \cdot R}_{= \mathbb{1} \cdot \mathbb{1} \cdot \mathbb{1} = \mathbb{1}} + \dots$$

$$= \mathbb{1} \left(1 + \frac{(\alpha t)^2}{2!} + \frac{(\alpha t)^4}{4!} + \dots\right) + R \left(\alpha t + \frac{(\alpha t)^3}{3!} + \dots\right)$$

$$= \mathbb{1} \cosh(\alpha t) + R \sinh(\alpha t) \text{ } \textcircled{O}$$

$$= v_0 e^{-\alpha t} \left[ \begin{pmatrix} \cosh(\alpha t) \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ \sinh(\alpha t) \end{pmatrix} \right] \text{ } \textcircled{O} \text{ wie (b) } \text{ } \textcircled{X}$$