

Nanoscopy

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 - Working principle
 - Variants
- 2 Deterministic localization microscopy
 - STED principle
 - STED PSF
- 3 Stochastic localization microscopy
 - Position fitting
 - Algorithm

$$M_l(x, y) = \int_{S_z} \text{PSF}(x, y, z) * (I(x, y, z) \cdot S_l(x, y, z)) dz \quad (1)$$

- Use multiple measurements M_l of the same fluorophores.
- Illumination $I(x, y, z)$ fixed: confocal or wide-field
- Use a change in the fluorophore $S_l(x, y, z)$ itself (i.e. toggle the fluorescence)
- Introducing **non-linearity** is important: allows for higher resolution improvement
- Two quite distinct approaches: Deterministic and stochastic

Deterministic methods

- Actively switch fluorophores into an on- or off-state
- Resolution improvement: switching occurs non-linear
- Typically uses (modified) confocal illumination
- Signal processing quite similar to standard confocal

Stochastic methods

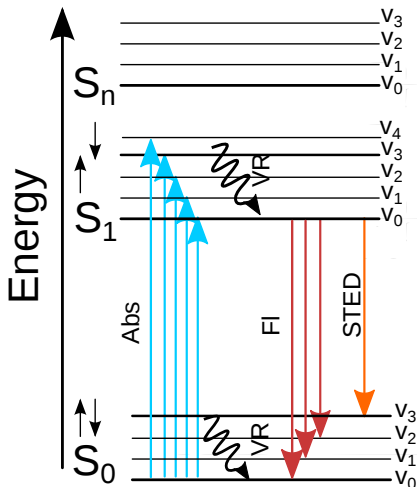
- Highly sensitive wide-field detection, high frame rate
- Induce fluorophore blinking: Most fluorophores off in most frames
- Ensure that the PSFs of remaining events to not overlap
- Post-process by detecting positions

Nobel prize 2014 for both STED (determ.) and PALM (stoch.)

Deterministic RESOLFT-techniques, here: STED

Three wavelength:

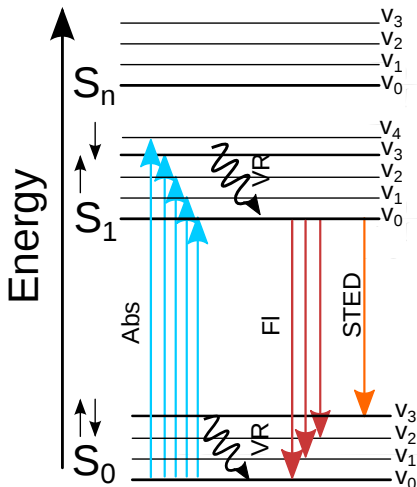
- Excitation: $S_0 V_0 \rightarrow S_1 V_k$, ground state into first excitation, short wavelength
- Stimulated emission: $S_1 V_0 \rightarrow S_0 V_n$. Ensure that λ_{STED} does not carry enough energy for excitation. Medium wavelength.
- Fluorescence: Emission $S_1 V_0 \rightarrow S_0 V_m$ with $m < n$. Filter out λ_{STED} with a sharp filter. Long wavelength.

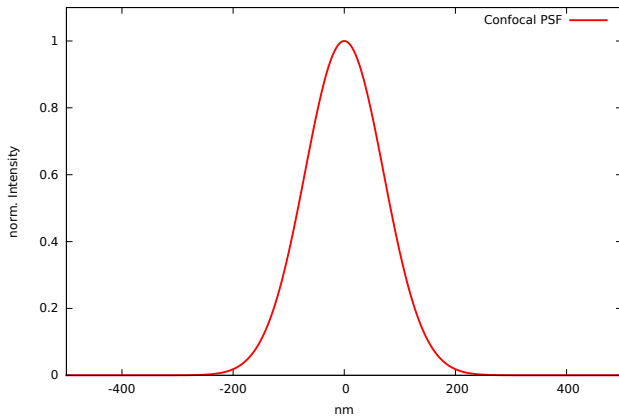


STED

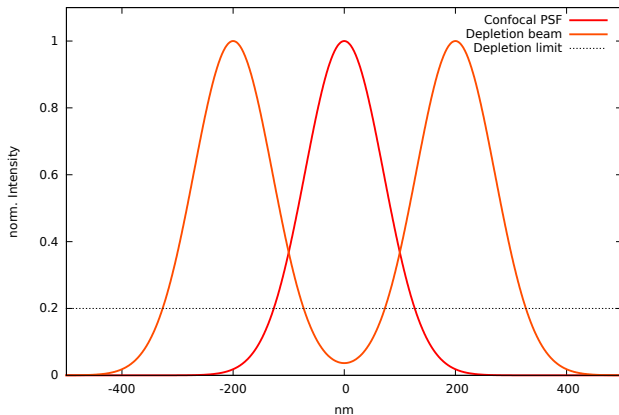
Properties of λ_{STED}

- with rising intensity, probability shifts towards the STED-enhanced transmission
- this process is non-linear, with a cut-off at (almost) full probability on the STED transition
- Intensities depend on fluorophores (probability) spectrum
- only measure the fluorescence *not* at λ_{STED} (steep filters)





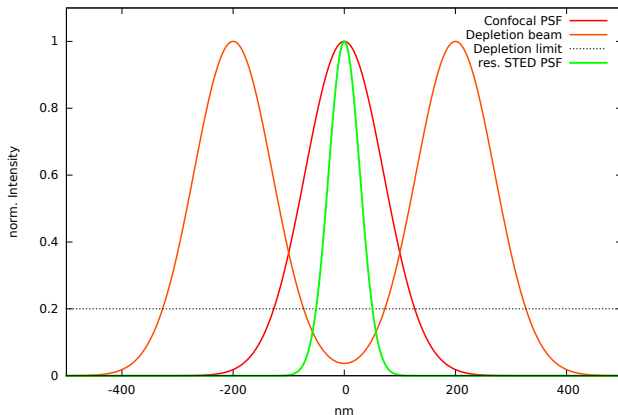
PSF for standard confocal excitation / detection



Add a (shaped) depletion beam

- Intensities (between beams) are arbitrary
- Assume here: $\frac{1}{5}$ intensity yields full depletion

STED - PSF



Result / STED PSF:

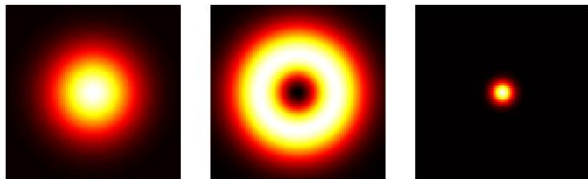
- Emission only for $I_{\text{ex.}} > 0$ and where $I_{\text{STED}} < 0.2$.
- STED PSF width now scales with I_{STED} .

STED - 2D PSF intensity profile

Resolution

$$d = \frac{\lambda}{2 \cdot \text{NA} \cdot \sqrt{1 + \frac{I_{\text{STED}}}{I_{\text{sat}}}}}$$

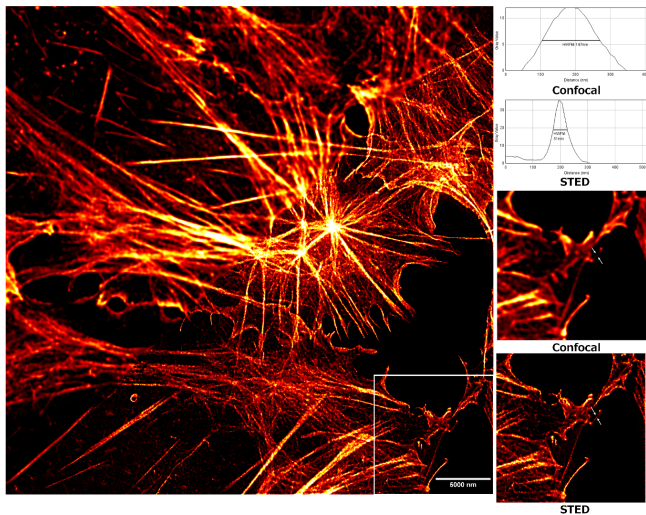
- Theory: No limit to resolution, just increase I_{STED}
- Reality: I_{STED} destroys the sample, even for modest resolutions
- 50nm for relevant samples, 2nm as proof-of-concept



Wikimedia / STED PSF

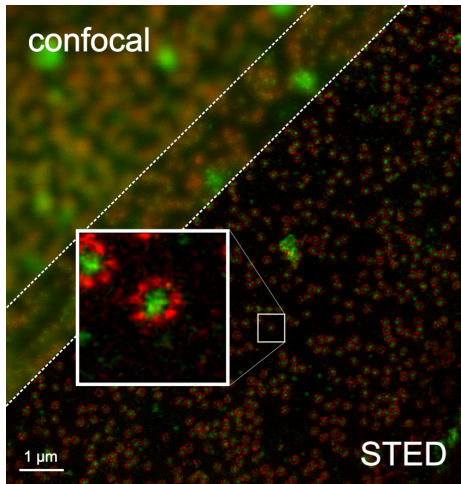
- Instrument: Confocal microscope with second STED beam
- Some diffraction element to form the doughnut

STED - Example (Actin)



Wikimedia / STED Actin 50nm

STED - Example (NPC)



Wikimedia / STED 2color NPC

RESOLFT: **R**eversible **S**aturable **O**ptical **F**luorescence **T**ransitions

GSD - ground-state depletion

- Same spatial beam layout as STED
- Instead of depletion, induce a transition to / from non-fluorescent triplet state: Switch the fluorophore on / off
- Slower (transition time), but less damaging (intensities)

RESOLFT with switchable dyes

- Same spatial beam layout as STED
- Proteins or organic dyes with switching wavelength
- Slower (even as GSD), photo-damage only dependent on dye switching properties

STED and RESOLFT - summary

- $\frac{1}{3}$ Nobel prize (Stefan Hell) awarded for STED
- First publications combine RESOLFT-like switching with SIM frequency shifting:
Even higher resolution
- Instrumentation: Confocal microscope with optical add-on, minimal post-processing
- Drawback / Trade-offs: Speed, resolution, intensity / photo-damage.
- No STED in Bielefeld

Stochastic localization microscopy

Stochastic localization microscopy

Idea

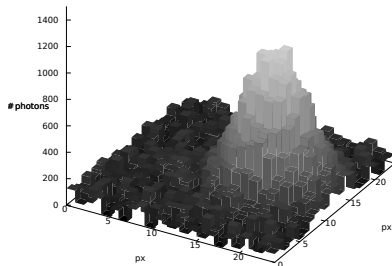
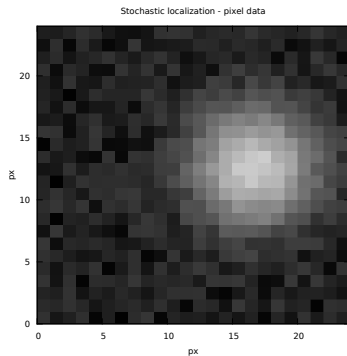
- Fluorophore: single molecule (sub-nanometer) emitting photons → point-source
- Photons distributed on sensor → Point-spread function
- Usual wide-field: overlap of all Fluorophore point-spread functions
- Idea: Observe a single fluorophore

Microscope

- Standard wide-field microscope (good NA)
- Sensitive camera: Events with $\sim 1,000 - 10,000$ photons
- Fast camera: Capture $\sim 2,000 - 50,000$ frames
- Multiple laser lines, some with high power
- All illumination modes (TIRF, HiLo, EPI)

A single fluorophore

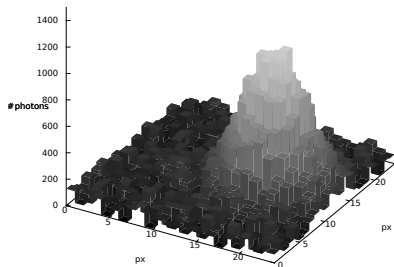
Stochastic localization - pixel data



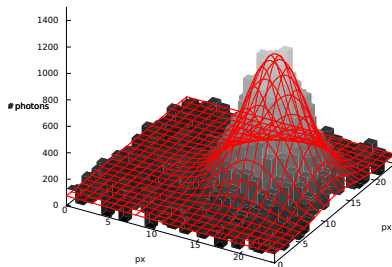
(simulated) intensity distribution, incl. photon shot noise
Reality: Larger pixels, less photons

Fitting the distribution

Stochastic localization - pixel data



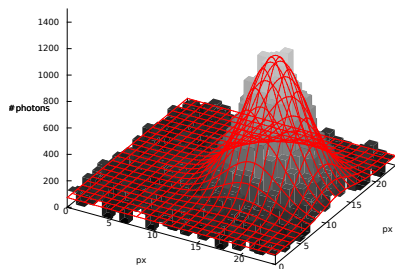
Stochastic localization - pixel data w. fit



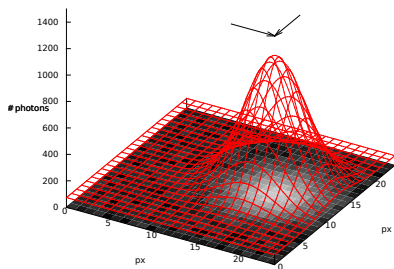
2D Gaussian fit to the emission

Fitting the distribution

Stochastic localization - pixel data w. fit



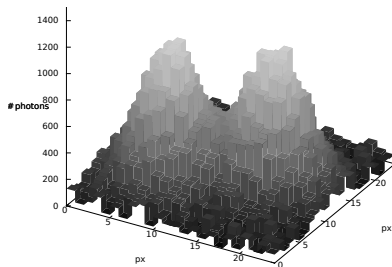
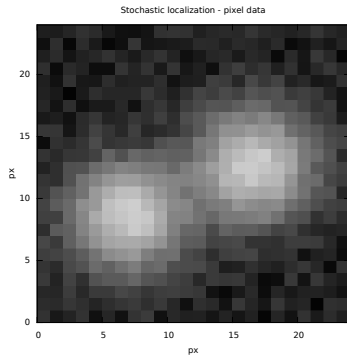
Stochastic localization - pixel data w. fit, localization



Fit yields: Position, Intensity, FWHM (all with fit precision)

Two fluorophores with enough distance

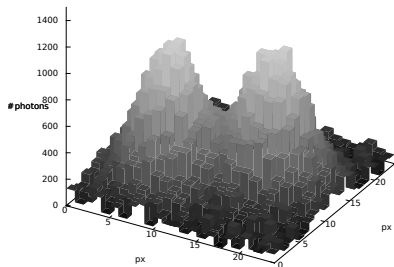
Stochastic localization - pixel data



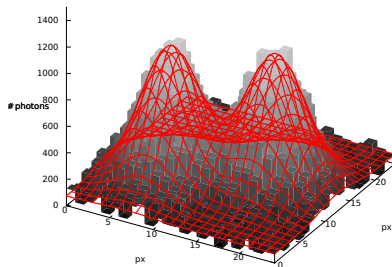
Emitter distance larger than FWHM

Fitting the distribution

Stochastic localization - pixel data



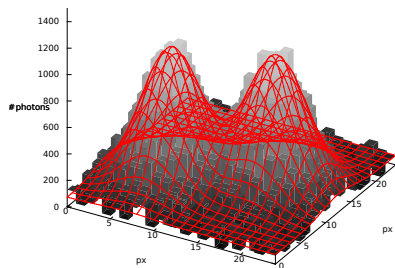
Stochastic localization - pixel data w. fit



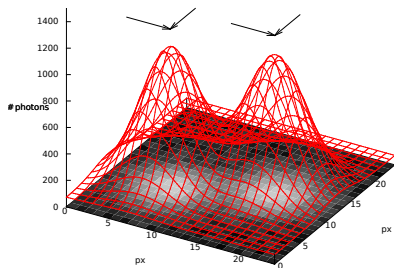
Gaussian fit still works

Fitting the distribution

Stochastic localization - pixel data w. fit



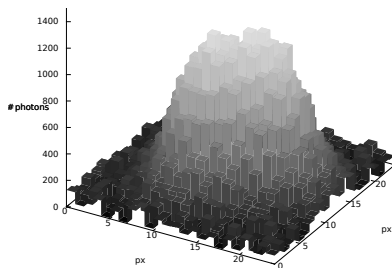
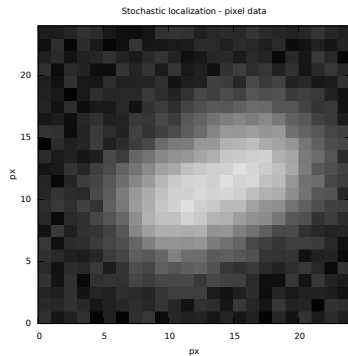
Stochastic localization - pixel data w. fit, localization



Position and intensity for each emitter

Fluorophores too close

Stochastic localization - pixel data



Fluorophores within FWHM: fit fails

Algorithm

For each frame:

- Find possible emitters (e.g. intensity)
- Fit Gaussian distribution
- Reject errors (emitters too close, ...)
- Store a long list, values and fit precision:
 - ▶ position
 - ▶ intensity
 - ▶ FWHM
 - ▶ frame number

(Fiji includes this as a plugin)

Next week:

- Sample preparation
- Resolution
- Visualization
- Extension to 3D