

Tutorial sheet 5

18. Faithful representation

Let \mathcal{G} be a group and \mathcal{D} a representation of \mathcal{G} . Show that \mathcal{D} is a faithful representation of the quotient group $\mathcal{G}/\ker \mathcal{D}$.

19. Representation of the Galilei group

In exercise 11. you already encountered the Galilei group $\text{Gal}(3)$.

i. Show that a 5-dimensional linear representation of $\text{Gal}(3)$ consists of the matrices of the type

$$\begin{pmatrix} \mathcal{R} & \vec{v} & \vec{a} \\ \vec{0}^\top & 1 & \tau \\ \vec{0}^\top & 0 & 1 \end{pmatrix}, \quad (1)$$

where $\vec{0}^\top$ denotes a row vector with three zero entries, while \vec{v} and \vec{a} are two column vectors with three arbitrary real entries and \mathcal{R} is a three-dimensional rotation matrix, $\mathcal{R} \in \text{SO}(3)$.

ii. Is this representation faithful? Is it fully reducible? (As you will learn later, the — negative — answer reflects the fact that the Galilei group is not compact.)

20. A matrix representation of a well-known finite group

Consider the $n \times n$ matrix

$$T = \begin{pmatrix} 0 & 1 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 1 & 0 & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 & 0 \\ 0 & 0 & 0 & \cdots & 0 & 1 \\ 1 & 0 & 0 & 0 & \cdots & 0 \end{pmatrix} \quad (2)$$

i.e. $T_{ij} = 1$ for all $j = i + 1$ and for $(i = m, j = 1)$, and otherwise $T_{ij} = 0$.

i. Construct a group $\tilde{\mathcal{G}}$ from T via matrix multiplication. The matrix group $\tilde{\mathcal{G}}$ is a representation of a finite group \mathcal{G} which you already know; which one?

ii. With the help of Maschke's theorem we know that the representation $\tilde{\mathcal{G}}$ is completely reducible. What are all irreducible representations of $\tilde{\mathcal{G}}$? Calculate for this purpose the eigenspaces of T .

21. Symmetry in a classical many-body system

Consider a planar molecule, in the absence of external forces, with $N > 1$ interacting atoms at coordinates $\mathbf{x}_{i,0} + \mathbf{x}_i \equiv (x_{i,0} + x_i, y_{i,0} + y_i)$ for $i \in \{1, \dots, N\}$, where $\mathbf{x}_{i,0} = (x_{i,0}, y_{i,0})$ is the equilibrium position of the i -th atom with mass m_i .

i. Explain why the part of the Hamilton function of the molecule relevant for the description of small oscillations of the atoms about their equilibrium positions may be written as

$$H = \frac{1}{2} \dot{\mathbf{X}}^\top M^2 \dot{\mathbf{X}} + \mathbf{X}^\top V \mathbf{X} \quad (3)$$

with $\mathbf{X} \equiv (x_1, y_1, x_2, y_2, \dots)$. What is the significance of the matrices M and V ?

ii. Show that if the molecule is invariant under the transformations $\mathbf{X} \rightarrow \mathbf{X}' = \mathcal{D}(g)^{-1}\mathbf{X}$, where \mathcal{D} is a $2N$ -dimensional representation of a group \mathcal{G} , then this implies the commutator $[V', \mathcal{D}'] = 0$ where $\mathcal{D}' = M\mathcal{D}M^{-1}$ and $V' = M^{-1}VM^{-1}$.

iii. A normal mode of the system is defined as a solution to the equations of motion in which all atoms oscillate with the same frequency. Show that for a normal mode, $M\mathbf{X}$ is an eigenvector of V' and that if $M\mathbf{X}$ is an eigenvector, then so is $\mathcal{D}'M\mathbf{X}$. Under which conditions is \mathcal{D}' a reducible representation and if so, what do the invariant subspaces correspond to?

iv. Let us consider two examples of the system with identical particles ($m_i = m$ for all $i \in \{1, \dots, N\}$), e.g. a benzene ring. The symmetry group \mathcal{G} will be in either case the cyclic group C_N , only the matrix representation will be different. In the first case the generator of the representation, T_1 , rotates each particle through the same angle, i.e.

$$\mathbf{x}_i \rightarrow \mathbf{x}'_i = \begin{pmatrix} \cos \frac{2\pi}{N} & \sin \frac{2\pi}{N} \\ -\sin \frac{2\pi}{N} & \cos \frac{2\pi}{N} \end{pmatrix} \mathbf{x}_i \quad (4)$$

In the second case, the generator of the representation, T_2 , performs a cyclic permutation of the particles, $\mathbf{x}_i \rightarrow \mathbf{x}'_i = \mathbf{x}_{i+1}$ for $i \in \{1, \dots, N-1\}$ and $\mathbf{x}_N \rightarrow \mathbf{x}'_N = \mathbf{x}_1$. What is the relation between these two representations? What does each of the two symmetries tell us about the matrix V ? Into which irreducible representations do the representations generated by T_1 and T_2 split?