

## Tutorial sheet 2

**Discussion topics:** What are the Lagrangian and Eulerian descriptions? How is a fluid defined?

### 4. Lagrangian description: Jacobian determinant

Consider the twice continuously differentiable ( $\mathcal{C}^2$ ) mapping  $(t, \vec{R}) \mapsto \vec{r}(t, \vec{R})$  from “initial” position vectors at  $t_0$  to those at time  $t$ . Let  $(X^1, X^2, X^3)$  resp.  $(x^1, x^2, x^3)$  denote the coordinates of  $\vec{R}$  resp.  $\vec{r}$  in some fixed system.

The *Jacobian determinant*  $J(t, \vec{R})$  of the transformation  $\vec{R} \mapsto \vec{r}$  is as usual the determinant of the matrix with elements  $\partial x^i / \partial X^j$ . Thanks to the hypotheses on the mapping  $\vec{r}(t, \vec{R})$ , this Jacobian has simple mathematical properties.

- i. Can you find a physical interpretation for  $J(t, \vec{R})$ ? [*Hint:* Think of small volume elements.]
- ii. Using the initial value  $J(t_0, \vec{R})$  in the reference configuration, as well as the invertibility and  $\mathcal{C}^2$ -character of the mapping  $\vec{r}(t, \vec{R})$ , show that  $J(t, \vec{R})$  is positive for  $t \geq t_0$ . What does this mean physically?
- iii. Consider the motion of a continuous medium defined for  $t \geq 0$  by

$$x^1 = X^1 + ktX^2, \quad x^2 = X^2 + ktX^1, \quad x^3 = X^3,$$

where  $k > 0$ . One may for simplicity assume that the coordinates are Cartesian.

- a) Over which time range is this motion defined? [*Hint:* Jacobian determinant!]
- b) What are its pathlines?
- c) Determine the Eulerian description of this motion, i.e. the velocity field  $\vec{v}(t, \vec{r})$ .

### 5. Stress tensor

Let  $\mathbf{T}_{ij}$  denote the Cartesian<sup>1</sup> components of the stress tensor in a continuous medium. Consider an infinitesimal cube of medium of side  $d\ell$ , whose sides are parallel to the axes of the coordinate system.

- i. Explain why the  $k$ -component  $\mathcal{M}_k$  of the torque exerted on the cube by the neighboring regions of the continuous medium obeys  $\mathcal{M}_k \propto -\epsilon_{ijk} \mathbf{T}_{ij} (d\ell)^3$ , with  $\epsilon_{ijk}$  the usual Levi-Civita symbol.
- ii. Using dimensional considerations, write down the dependence of the moment of inertia  $I$  of the cube on  $d\ell$  and on the continuum mass density  $\rho$ .
- iii. Using the results of the previous two questions, how does the rate of change of the angular velocity  $\omega_k$  scale with  $d\ell$ ? How can you prevent this rate of change from diverging in the limit  $d\ell \rightarrow 0$ ?

### 6. Isotropy of pressure

Consider a geometrical point at position  $\vec{r}$  in a fluid at rest. The stress vector across every surface element going through this point is normal:  $\vec{T}(\vec{r}) = -\mathcal{P}(\vec{r}) \vec{e}_n$ , with  $\vec{e}_n$  the unit vector orthogonal to the surface element under consideration. Show that the (hydrostatic) pressure  $\mathcal{P}$  is independent of the orientation of  $\vec{e}_n$ .

*Hint:* Consider the forces on the faces of an infinitesimal trirectangular tetrahedron.

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<sup>1</sup>... which allows us to be sloppy with the position of indices.