

Fundamental equations of nonrelativistic fluid dynamics

Fundamental equations of nonrelativistic fluid dynamics

- Reynolds' transport theorem

- Equations of motion of a perfect fluid

May 11 & 18

- Equations of motion of a Newtonian fluid

June 8 & 15

Throughout these slides, Cartesian coordinates ($\{x_j\}$, $\{v_j\}$, ...) are used:

$$x_j = x^j, v_j = v^j \dots \text{ for } j = 1, 2, 3$$

Momentum law for a real fluid

In a real (\neq perfect) fluid, friction forces and heat transport are no longer neglected.

The momentum-flux tensor can take a more complicated form than in the perfect-fluid case (cf. slide 13):

$$\mathbf{T}^{ij}(t, \vec{r}) \equiv \mathcal{P}(t, \vec{r}) \delta^{ij} + \rho(t, \vec{r}) v^i(t, \vec{r}) v^j(t, \vec{r}) + \pi^{ij}(t, \vec{r})$$

where the “viscous stress tensor” $\pi^{ij}(t, \vec{r})$ is function of the derivatives of the velocity field (and possibly of other thermodynamical quantities).

For a “Newtonian fluid”:

$$\pi^{ij}(t, \vec{r}) \equiv -\eta(t, \vec{r}) \left[\frac{\partial v^i(t, \vec{r})}{\partial x^j} + \frac{\partial v^j(t, \vec{r})}{\partial x^i} - \frac{2}{3} [\vec{\nabla} \cdot \vec{v}(t, \vec{r})] \delta^{ij}(t, \vec{r}) \right] - \zeta(t, \vec{r}) [\vec{\nabla} \cdot \vec{v}(t, \vec{r})] \delta^{ij}(t, \vec{r})$$

traceless
diagonal

Momentum law for a Newtonian fluid

... reads
$$\frac{\partial}{\partial t} [\rho(t, \vec{r}) \mathbf{v}^i(t, \vec{r})] + \sum_{j=1}^3 \frac{\partial \mathbf{T}^{ij}(t, \vec{r})}{\partial x^j} = f_V^i(t, \vec{r})$$

where

$$\mathbf{T}^{ij}(t, \vec{r}) \equiv \mathcal{P}(t, \vec{r}) \delta^{ij} + \rho(t, \vec{r}) v^i(t, \vec{r}) v^j(t, \vec{r}) + \pi^{ij}(t, \vec{r})$$

with

$$\begin{aligned} \pi^{ij}(t, \vec{r}) \equiv & -\eta(t, \vec{r}) \left[\frac{\partial v^i(t, \vec{r})}{\partial x^j} + \frac{\partial v^j(t, \vec{r})}{\partial x^i} - \frac{2}{3} [\vec{\nabla} \cdot \vec{v}(t, \vec{r})] \delta^{ij}(t, \vec{r}) \right] \\ & - \zeta(t, \vec{r}) [\vec{\nabla} \cdot \vec{v}(t, \vec{r})] \delta^{ij}(t, \vec{r}) \end{aligned}$$

- η : shear viscosity – multiplies the shear stress tensor
- ζ : bulk (or second) viscosity – multiplies the volume expansion rate $\vec{\nabla} \cdot \vec{v}(t, \vec{r})$: only relevant in compressible flows!

Momentum law for a Newtonian fluid

Navier–Stokes equation

$$\rho(t, \vec{r}) \left\{ \frac{\partial \vec{v}(t, \vec{r})}{\partial t} + [\vec{v}(t, \vec{r}) \cdot \vec{\nabla}] \vec{v}(t, \vec{r}) \right\} = -\vec{\nabla} \mathcal{P}(t, \vec{r}) + \vec{f}_V(t, \vec{r}) + \eta \Delta \vec{v}(t, \vec{r}) + \left(\zeta + \frac{\eta}{3} \right) \vec{\nabla} [\vec{\nabla} \cdot \vec{v}(t, \vec{r})]$$

- η : shear viscosity
- ζ : bulk viscosity
- $\nu \equiv \eta/\rho$: kinematic shear viscosity

η, ζ : Pa·s (= "Poiseuille" [pronounce: \approx Puasöj]); ν : m²·s⁻¹

Momentum law for a Newtonian fluid

Navier–Stokes equation

$$\rho(t, \vec{r}) \left\{ \frac{\partial \vec{v}(t, \vec{r})}{\partial t} + [\vec{v}(t, \vec{r}) \cdot \vec{\nabla}] \vec{v}(t, \vec{r}) \right\} = -\vec{\nabla} \mathcal{P}(t, \vec{r}) + \vec{f}_V(t, \vec{r}) + \eta \Delta \vec{v}(t, \vec{r}) + \left(\zeta + \frac{\eta}{3} \right) \vec{\nabla} [\vec{\nabla} \cdot \vec{v}(t, \vec{r})]$$

Boundary conditions:

- at a wall or an obstacle, “impermeability” + “no slip” (friction!)
👉 relative velocity vanishes

Force exerted by a Newtonian fluid

Stress vector (cf. lecture I) on a small surface element

$$\vec{T}_s(t, \vec{r}) = \sum_{i,j=1}^3 \left\{ \left[-\mathcal{P}(t, \vec{r}) + \left(\zeta - \frac{2}{3}\eta \right) \vec{\nabla} \cdot \vec{v}(t, \vec{r}) \right] \delta^i_j + \eta \left[\frac{\partial v^i(t, \vec{r})}{\partial x^j} + \frac{\partial v^j(t, \vec{r})}{\partial x^i} \right] \right\} n^j(\vec{r}) \vec{e}_i$$

with $\vec{e}_n(\vec{r}) \equiv \sum_i n^i(\vec{r}) \vec{e}_i$ normal unit vector to the surface element.

- First line: normal stress: hydrostatic pressure + viscous part (absent in an incompressible flow).
- Second line: tangential stress

Energy balance in a Newtonian fluid

... in the presence of conservative forces $\vec{f}_V(\vec{r}) = -\rho(\vec{r})\vec{\nabla}\Phi(\vec{r})$

$$\begin{aligned} & \frac{\partial}{\partial t} \left[\frac{1}{2} \rho(t, \vec{r}) \vec{v}(t, \vec{r})^2 + e(t, \vec{r}) + \rho(t, \vec{r}) \Phi(t, \vec{r}) \right] \\ & + \vec{\nabla} \cdot \left\{ \left[\frac{1}{2} \rho(t, \vec{r}) \vec{v}(t, \vec{r})^2 + e(t, \vec{r}) + \mathcal{P}(t, \vec{r}) + \rho(t, \vec{r}) \Phi(t, \vec{r}) \right] \vec{v}(t, \vec{r}) \right. \\ & \quad - \eta \left[\left(\vec{v}(t, \vec{r}) \cdot \vec{\nabla} \right) \vec{v}(t, \vec{r}) + \vec{\nabla} \left(\frac{\vec{v}(t, \vec{r})^2}{2} \right) \right] \\ & \quad \left. - \left(\zeta - \frac{2\eta}{3} \right) \left[\vec{\nabla} \cdot \vec{v}(t, \vec{r}) \right] \vec{v}(t, \vec{r}) - \kappa \vec{\nabla} T(t, \vec{r}) \right\} = 0 \end{aligned}$$

● Viscous forces (shear + bulk) exert work

● Heat is transported: heat current $\vec{j}_Q(t, \vec{r}) = -\kappa \vec{\nabla} T(t, \vec{r})$

Fourier's law

Entropy balance in a Newtonian fluid

$$\frac{\partial s(t, \vec{r})}{\partial t} + \vec{\nabla} \cdot \left[s(t, \vec{r}) \vec{v}(t, \vec{r}) - \kappa \frac{\vec{\nabla} T(t, \vec{r})}{T(t, \vec{r})} \right] = \frac{1}{T(t, \vec{r})} \left\{ 2\eta \mathbf{S}(t, \vec{r}) : \mathbf{S}(t, \vec{r}) + \zeta [\vec{\nabla} \cdot \vec{v}(t, \vec{r})]^2 + \kappa \frac{[\vec{\nabla} T(t, \vec{r})]^2}{T(t, \vec{r})} \right\}$$

with

$$\mathbf{S}(t, \vec{r}) : \mathbf{S}(t, \vec{r}) \equiv \sum_{i,j=1}^3 \mathbf{S}_{ij}(t, \vec{r}) \mathbf{S}_{ij}(t, \vec{r})$$

$$\mathbf{S}_{ij}(t, \vec{r}) \equiv \frac{1}{2} \left[\frac{\partial v^i(t, \vec{r})}{\partial x^j} + \frac{\partial v^j(t, \vec{r})}{\partial x^i} - \frac{2\delta^{ij}}{3} \vec{\nabla} \cdot \vec{v}(t, \vec{r}) \right]$$

Entropy increases (second law!) if η , ζ , and κ are positive.