

2.2 Perturbation theory

Now write  $L = L_0 + L_{int}$

quadratic in  $\varphi$ ,  $\partial\varphi$

example:  $L_{int} = -\frac{\lambda}{4}\varphi^4$

$Z = \int \mathcal{D}\varphi e^{i(S_0 + L_{int})}$  Expand the exponential

$$Z = \int \mathcal{D}\varphi e^{iS_0} \left[ 1 + iL_{int} + \frac{1}{2}(iL_{int})^2 + \dots \right]$$

$$= Z_0 \left[ 1 + \langle iL_{int} \rangle_0 + \frac{1}{2} \langle (iL_{int})^2 \rangle_0 + \dots \right]$$

with

$$\langle A \rangle_0 := \frac{\int \mathcal{D}\varphi e^{iS_0} A}{\int \mathcal{D}\varphi e^{iS_0}} \quad \text{"expectation value"}$$

N.B: any temperature dependent factor in the integration measure drop out here

For the pressure  $P$  we had  $Z = \exp(\beta PV)$ ,  $P = T \ln Z / V$

$$\ln(1+x) = x - \frac{x^2}{2} + \dots$$

$$\ln Z = \ln Z_0 + \langle iL_{int} \rangle_0 + \frac{1}{2} \langle (iL_{int})^2 \rangle_0 - \frac{1}{2} (\langle iL_{int} \rangle_0)^2 + \dots$$

$$P = P_0 + \frac{T}{V} \left[ \langle iL_{int} \rangle_0 + \frac{1}{2} \langle (iL_{int})^2 \rangle_0 - \frac{1}{2} (\langle iL_{int} \rangle_0)^2 + \dots \right]$$

If we insert an expression for  $L_{int}$  we see that we need to compute expectation values like

$$\langle \varphi(x_1) \varphi(x_2) \dots \varphi(x_n) \rangle_0$$

Wick's theorem: for any even  $n$

$$\langle \varphi(x_1) \cdots \varphi(x_n) \rangle_0 = \sum_{\text{contractions}} \langle \varphi(x'_1) \varphi(x'_2) \rangle_0 \cdots \langle \varphi(x'_{n-1}) \varphi(x'_n) \rangle_0$$

$$\{x_1, \dots, x_n\} = \{x'_1, \dots, x'_n\}$$

contractions: pairings of  $x_1, \dots, x_n$

example:  $n=4$

$$\begin{aligned} \langle \varphi(x_1) \cdots \varphi(x_4) \rangle_0 &= \langle \varphi(x_1) \varphi(x_2) \rangle_0 \langle \varphi(x_3) \varphi(x_4) \rangle_0 \\ &+ \langle \varphi(x_1) \varphi(x_3) \rangle_0 \langle \varphi(x_2) \varphi(x_4) \rangle_0 \\ &+ \langle \varphi(x_1) \varphi(x_4) \rangle_0 \langle \varphi(x_2) \varphi(x_3) \rangle_0 \end{aligned}$$

graphical interpretation:

$$\begin{array}{cccc} 1 & \bullet & \bullet & 4 \\ & \cdot & \cdot & \\ 2 & \bullet & \bullet & 3 \end{array} = \begin{array}{c} | \\ | \end{array} \begin{array}{c} | \\ | \end{array} + \begin{array}{c} \diagup \diagdown \\ \diagdown \diagup \end{array} + \begin{array}{c} \text{---} \\ \text{---} \end{array}$$

N.B: Wick's theorem is a general property of Gauss-integrals

How to compute  $\langle \varphi(x_1) \varphi(x_2) \rangle_0$ ?

For this we will make use of the Fourier representation of  $\varphi$ :

$$\varphi \text{ periodic} \Rightarrow \varphi(-i\beta, \vec{x}) = \varphi(0, \vec{x}) \Rightarrow$$

$\varphi$  can be expanded in a Fourier series

$$\varphi(-i\tau, \vec{x}) = \tau \sum_{n \in \mathbb{Z}} e^{-i\omega_n \tau} \varphi_n(\vec{x})$$

$$\omega_n = n 2\pi T$$

Matsubara frequencies

$$\varphi_n(\vec{x}) = \int_0^\beta d\tau e^{i\omega_n \tau} \varphi(-i\tau, \vec{x})$$

We also use the functional derivative defined through

$$(i) \quad \frac{\delta}{\delta \varphi(x)} \varphi(x') = \delta(x-x') \quad (= \delta^{(4)}(x-x'))$$

(ii)  $\frac{\delta}{\delta \varphi(x)}$  satisfies the product rule

$$(*) \quad \text{Def} \quad Z_0[J] := \frac{\int \mathcal{D}\varphi \exp\left\{i\left(S_0 + \int d^4x J(x)\varphi(x)\right)\right\}}{\int \mathcal{D}\varphi e^{iS_0}} \quad \text{generating functional}$$

This is a functional of the field  $J$ . Expectation values of  $\varphi$  are obtained by functional differentiation:

$$\langle \varphi(x_1) \varphi(x_2) \rangle_0 = \frac{\delta Z_0[J]}{i\delta J(x_1) i\delta J(x_2)} \Big|_{J=0}$$

Now compute  $Z_0[J]$ .  $\int d^4x \frac{1}{2} \varphi \partial^2 \varphi \stackrel{\text{IBP}}{=} -\int \varphi \partial^2 \varphi \Rightarrow$

$$S_0 + \int d^4x J \varphi = \int d^4x \left\{ -\frac{1}{2} \varphi (\partial^2 + m^2) \varphi + J \varphi \right\}$$

where  $\int d^4x \equiv \int_0^\beta dt \int d^3x$

Complete the square by shifting the integration

variable  $\varphi \rightarrow \varphi + \varphi'$  in (\*), where  $\varphi'$  will be determined

shortly. Use  $\int d^4x \varphi' (\partial^2 + m^2) \varphi = \int d^4x \varphi (\partial^2 + m^2) \varphi' \Rightarrow$

$$S_0 + \int d^4x J \varphi \rightarrow \int d^4x \left\{ -\frac{1}{2} \varphi (\partial^2 + m^2) \varphi - \varphi (\partial^2 + m^2) \varphi' - \frac{1}{2} \varphi' (\partial^2 + m^2) \varphi' + J \varphi + J \varphi' \right\}$$

Choose  $\varphi'$  such that

$$(**) \quad (\partial^2 + m^2)\varphi' = J$$

Then the terms linear in  $\varphi$  cancel, and the integral over  $\varphi$  is  $\int \mathcal{D}\varphi e^{iS_0}$  which cancels in  $(*)$ .

Solve  $(**)$  by FT: [ $J$  should also be periodic]

$$\partial^2 = \partial_t^2 - \nabla^2 = -\partial_\tau^2 - \nabla^2 \xrightarrow{\text{FT}} \omega_n^2 + \vec{k}^2 = -k^2$$

Write:  $k^0 = i\omega_n \Rightarrow$

$$\varphi'_n(\vec{k}) = \Delta(k) J_n(\vec{k}) \quad \text{with}$$

$$\Delta(k) := \frac{1}{-k^2 + m^2} = \frac{1}{\omega_n^2 + \vec{k}^2 + m^2}$$

NB: unlike in real time we don't need an  $i\epsilon$ -prescription

Inverse FT  $\rightarrow$

$$\begin{aligned} \varphi'(-i\tau, \vec{x}) &= T \sum_n \int \frac{d^3 k}{(2\pi)^3} e^{-i\omega_n \tau} e^{i\vec{k}\vec{x}} \Delta(k) J_n(\vec{k}) \\ &= \int_0^\beta d\tau' \int d^3 x' e^{i\omega_n \tau'} e^{-i\vec{k}\vec{x}'} J(x') \\ &= \int_0^\beta d\tau' \int d^3 x' \Delta(x-x') J(x') \end{aligned}$$

where

$$\Delta(x-x') = T \sum_n \int \frac{d^3 k}{(2\pi)^3} e^{-i\omega_n(\tau-\tau')} e^{i\vec{k}(\vec{x}-\vec{x}')} \Delta(k)$$

Then

$$\begin{aligned} Z_0[J] &= \exp \left\{ i \int d^4 x \left[ \underbrace{-\frac{1}{2} \varphi' (\partial^2 + m^2) \varphi'}_{= J} + J \varphi' \right] \right\} \Rightarrow \\ &= \frac{1}{2} J \varphi' \end{aligned}$$

Now  $Z_0[J]$

Write

$$\varphi'(x) = i \int d^4x' \Delta(x-x') J(x')$$
 which gives

$$Z_0[J] = \exp\left\{-\frac{1}{2} \int d^4x \int d^4x' J(x) \Delta(x-x') J(x')\right\}$$

more explicitly:

$$Z_0[J] = \exp\left\{\frac{1}{2} \int_0^\beta dt \int d^3x \int_0^\beta dt' \int d^3x' J(-it, \vec{x}) \Delta(-i(t-t'), \vec{x}-\vec{x}') J(-it', \vec{x}')\right\}$$

In any case, we obtain

$$\langle \varphi(x_1) \varphi(x_2) \rangle_0 = \Delta(x_1 - x_2)$$

One can also use our result to compute  $n$ -point functions and to check Wick's theorem.